FastFlow: Performance and Productivity in the Multicore Era

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Issues for multicore era
- Mostly focusing on shared memory hardware

High-level patterns & FastFlow

The challenge for Formal methods.
- Questions and thoughts in this context (in open order)
- How our work might benefit or influence on formal method community
**ISSUEs for exascale era**

- Increasing scalability requires to decrease concurrency grain
- Programming systems should be designed to support fast data movement and enforce locality
  - It is not about Flops, it is about data movement
- Novel computing models are needed
  - A computer language is not a computing model. A library is not a computing model.
void Emitter () {
    for ( i =0; i <streamLen;++i){
        task = create_task ();
        queue=SELECT_WORKER_QUEUE();
        queue ->PUSH(task);
    }
}

void Worker() {
    while (!end_of_stream){
        myqueue ->POP(&task);
        do_work(task) ;
    }
}

int main () {
    spawn_thread( Emitter ) ;
    for ( i =0; i <nworkers;++i){
        spawn_thread(Worker);
    }
    wait_end () ;
}
Task farm with POSIX lock/unlock

![Diagram of task farm with POSIX lock/unlock]

- Speedup vs. Number of Cores
- Ideal, 50 μS, 5 μS, 0.5 μS
- Average execution time per task

Speedup

Number of Cores

2 3 4 5 6 7 8
Can we avoid locks?

- Under relaxed memory models, using CAS/atomic ops
  - "lock-free" data structures
  - they perform better than lock-based
  - they fence the memory and pay cache coherency reconciliation overhead
CompareAndSwap queues

![Diagram showing parallel processing with speedup against number of cores.](image)
Lock vs CAS at fine grain (0.5 μS)
Re-starting from the basics

- Reducing the problem to the bare bones
  - Producer-Consumer model (streaming)
  - Directly control thread blocking using non-blocking synchronizations
  - Directly design the “data channel”
    - Having clear how data move in the whole memory hierarchy

- Restarting from the FIFO queue
Interaction models: theoretical background

- Low-level synchronisation in the shared memory model
  - Mutual Exclusion (mutex)
    - typically used as basic building block of synchronisations
  - Producer Consumer

- They are not equally demanding
  - Mutual Exclusion is inherently more complex since requires deadlock-freedom
    - require interlocked ops (CAS, ...), that induces memory fences, thus cache invalidation
    - Dekker and Bakery requires Sequential Consistency (++)
  - Producer Consumer is a cooperative (non cyclic) process
FastFlow SPSC queues

Lamport FIFO - 1983

```c
push_nonbocking(data) {
    if (NEXT(head) == tail) {
        return EWOULDBLOCK;
    }
    buffer[head] = data;
    head = NEXT(head);
    return 0;
}

pop_nonblocking(data) {
    if (head == tail) {
        return EWOULDBLOCK;
    }
    data = buffer[head];
    tail = NEXT(tail);
    return 0;
}
```

FastFlow FIFO - derived from PICI 1997

```c
push_nonbocking(data) {
    if (NULL != buffer[head]) {
        return EWOULDBLOCK;
    }
    buffer[head] = data;
    head = NEXT(head);
    return 0;
}

pop_nonblocking(data) {
    data = buffer[tail];
    if (NULL == data) {
        return EWOULDBLOCK;
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```
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  data = buffer[tail];  
  if (NULL == data) {  
    return EWOULDBLOCK;  
  }  
  buffer[tail] = NULL;  
  tail = NEXT(tail);  
  return 0;  
}
```

- head and tail are mutually invalidated by producer and consumer
- 1 cache miss every push and pop (at least)
- producer read/write
- consumer read/write
- head
- tail
- no misses
- excluding “true” deps
- extended domain on void *
Recall: Two features - two problems

Memory/Cache Coherence
- Deal with multiple replicas of the same location in different caches

Memory Consistency
- Deal with the ordering in which writes and reads at different locations take effect in memory (issued by either the same or different processors/cores)
Memory Consistency

Processors:
- x86, x86_64: Total Store Order
- PowerPC: Weak Ordering (PowerEN?)
- ARM Cortex: Weak Ordering
- Alpha: Release Consistency

Any Sequential Consistency?
- No! It is not efficient
Can both “if” be evaluated to TRUE?

- Ideally NO, under Sequential Consistency NO
- Under more relaxed models? Not guaranteed ...

Java memory model doesn’t expose this complexity

- at the price of performance
FastFlow SPSC queues

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        return EWOULDBLOCK;
    }
    data = buffer[tail];
    tail = NEXT(tail);
    return 0;
}
```

- Proved to be correct under SC
- doesn’t work under weaker models

Lamport FIFO - 1983
FastFlow SPSC queues

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    buffer[head] = data;
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```

FastFlow FIFO - derived from PICI 1997

(WMB) For any model weaker than TSO

For any model weaker than TSO
FastFlow SPSC queues

![Graph 1: Nanoseconds per Operation vs Queue Size](image1)

- 0 ns
- 50 ns
- 100 ns
- 200 ns
- 400 ns
- 800 ns

![Graph 2: Nanoseconds per Operation vs Queue Size](image2)

- 0 ns
- 50 ns
- 100 ns
- 200 ns
- 400 ns
- 800 ns

Queue Size: 128, 192, 256, 2048

Nanoseconds per Operation
High-level patterns & FastFlow
Pattern-based approach: rationale

- Abstract parallelism exploitation pattern by parametric code
  - e.g. higher order function, code factories, C++ templates, ...
  - Hopefully, in such a way they can composed and nested as programming language constructs

- Provide user with mechanisms to specify the parameters
  - functional (seq code) and extra-functional (QoS) parameters

- Provide state-of-the-art implementation of each parallelism exploitation pattern
FastFlow: architecture

High-level programming
- Lock-free/fence-free non-blocking synchronisations
- C++ STL-like implementation
E.g. farm (a.k.a. master-worker)

- Common paradigm
  - Model foreach and Divide & Conquer
  - Can be used to build data-flow engine
  - Exploit it as a high-order language construct
    - A C++ template factory exploiting highly optimised implementation
E.g. farm (a.k.a. master-worker)

- **Common paradigm** (compute something)
  - Model foreach and Divide & Conquer
  - Can be used to build data-flow engine
  - Exploit it as a high-order language construct
    - A C++ template factory exploiting highly optimised implementation
The code

```cpp
using namespace ff;

class Worker: public ff_node {
public:
    void * svc(void * task) {
        int * t = (int *)task;
        std::cout << "Worker " << ff_node::get_my_id()
            << " received task " << *t << "\n";
        return task;
    }
};

class Collector: public ff_node {
public:
    void * svc(void * task) {
        int * t = (int *)task;
        if (*t == -1) return NULL;
        return task;
    }
};

class Emitter: public ff_node {
public:
    Emitter(int max_task): ntask(max_task) {}
    void * svc(void *) {
        int * task = new int(ntask);
        --ntask;
        if (ntask<0) return NULL;
        return task;
    }
private:
    int ntask;
};

int main(int argc, char * argv[]) {
    if (argc<3) {
        std::cerr << "use: ">
            << argv[0]
            << " nworkers streamlen\n";
        return -1;
    }
    int nworkers=atoi(argv[1]);
    int streamlen=atoi(argv[2]);
    if (!nworkers || !streamlen) {
        std::cerr << "Wrong parameters values\n";
        return -1;
    }
    ff_farm<> farm; // farm object
    Emitter E(streamlen);
    farm.add_emitter(&E);
    std::vector<ff_node *> w;
    for(int i=0;i<nworkers;++i) w.push_back(new Worker);
    farm.add_workers(w); // add all workers to the farm
    Collector C;
    farm.add_collector(&C);
    if (farm.run_and_wait_end()<0) {
        error("running farm\n");
        return -1;
    }
    std::cerr << "DONE, time= " << farm.ffTime() << " (ms)\n";
    farm.ffStats(std::cerr);
    return 0;
}
```
Medium grain (5 µS workload)
Edge-preserving denoiser. Live demo!

Lena* with 90% of noise is restored in 4 seconds
Next best result in literature is about 180 seconds
Pattern composition

✴ C++ STL-like implementation
  ✦ used to generatively compile skeletons into streaming networks
  ✦ fully memory barrier free implementation

✴ High-level pattern compose with ; and { }
  ✦ their implementation as parametric streaming networks (graphs)
  ✦ performance can be optimised as in streaming graphs (network of queues)
Patterns, and they comp. implementation

- farm
- pipe
- farm{ pipe }
- farm ; farm
- D&C = farm + wrap
- any variation of them requiring additional synch ...
The challenge for Formal methods. Questions and thoughts in this context (in open order).
Many open problems

1) Mechanisms e concurrency theory
   - new queues and data containers, new allocation techniques, ...
   - cc-NUMA: mapping tools; smart-network support (RDMA)

2) Formal Quantitative
   - performance analysis, optimisation, ...

3) Formal Qualitative
   - correctness, protocol proofs, ...

4) Design and tools
   - language evolution, compiler evolution, new features, meta-programming technique evolution, staged compilation, adaptive support
From patterns to metal

* Graphs can be used as compilation (intermediate) layer

* Is this good or a bad news?
  - Graphs well understood
    - Thread pinning, thread affinity, addresses locality, concurrent code optimisation, ..., can be modelled as graph
    - Traditional tool of formal method community
  - Everything concerning “graph” is complex by its very nature
    - At least for myself
**Simple?**

**SHR Inference rules...in one slide**

**Parallel**

\[
\Gamma \vdash G_1 \xrightarrow{\Delta} \Phi \vdash G_2 \quad \Gamma' \vdash G'_1 \xrightarrow{\Delta'} \Phi' \vdash G'_2 \\
\frac{(\Gamma \cup \Phi) \cap (\Gamma' \cup \Phi') = \emptyset}{\Gamma, \Gamma' \vdash G_1 \mid G_1' \xrightarrow{\Delta \cup \Delta'} \Phi, \Phi' \vdash G_2 \mid G_2'}
\]

The system can do whatever disjoint subsystems do.

**Restrict**

\[
\Gamma, x \vdash G_1 \xrightarrow{\Delta} \Gamma, x \vdash G_2 \\
\frac{\Lambda(x) = \epsilon \lor \Lambda(x) = \tau}{\Gamma \vdash \nu x \ G_1 \xrightarrow{\Lambda \setminus \{x\}} \Gamma \vdash \nu x \ G_2}
\]

The system can do any transition not requiring any synchronisations on restricted node.

**Merge**

\[
\Gamma, x, y \vdash G_1 \xrightarrow{\Delta} \Phi \vdash G_2 \\
\frac{\Gamma[x/y] \vdash G_1[x/y] \xrightarrow{\Lambda, \{x, \tau\}} \Phi[x/y] \vdash \nu U G_2[x/y] \rho}{\Gamma[x/y] \vdash G_1[x/y] \xrightarrow{\Lambda, \{x, \tau\}} \Phi[x/y] \vdash \nu U G_2[x/y] \rho}
\]

x and y can be fused provided that they perform compatible synchronisation actions.

---

E. Tuosto and myself.
Towards a Formal Semantics for Autonomic Components. Sensoria and CoreGRID FP6
Programming model

- Producer-Consumer and mutual exclusion have a different pragmatics: cooperation vs competition
- FastFlow advocates Producer-Consumer
  - Synchronisation via message-passing, data exchange via both message-passing and shared memory
  - Allow mutual exclusion on business code under the full responsibility of the programmer because this is not efficient at fine grain
    - They are additional bi-directional arrows in the graph
- IBM BlueGene/Q (forthcoming) has hardware transactional memory
  - LL/SC with versions
  - Efficient
A simple proof system for lock-free concurrency

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June 20, 2011

Non-blocking Primitives

CAS (loc, vold, vnew) atomically exchange the value in the memory location loc with value vnew, provided the current value in loc is vold.

LoadLink (LL) / StoreConditional (SC)

The pair of primitives have a transaction-like semantics:

- LL(loc) returns the address of the memory location loc
  May be interpreted as the transaction start
- SC(loc, v) tries to store v in the memory location loc:
  if the location has not been written by any concurrent thread since LL, v is written atomically and the instruction returns true; otherwise, it returns false, not writing the value
  May be interpreted as the transaction commit, returning either “success” or “abort”
A More Efficient and Type-Safe Version of FastFlow *

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Abstract. Nowadays, one of the most important challenges in programming is the efficient usage of multicore processors. Many new programming languages and libraries support multicore programming. FastFlow is one of the most promising multicore C++ libraries. Unfortunately, a design problem occurs in the library. One of the most important methods is pure virtual function in a base class. This method supports the communication between different threads. Although, it cannot be template function because of the virtuality, hence, the threads pass and take argument as a void* pointer. The base class is not template neither. This is not typesafe approach. We make the library more efficient and safer with the help of generative technologies.
Example: FF-allocator
Example: FF-allocator
Example: FF-allocator

- Faster than posix, hoard, TBB
- Unpublished, but available on sourceforge

The graph is now cyclic (with bound queues)
ISSUEs for exascale era

✴ A computer language is not a computing model. A library is not a computing model.

✦ Data communication happen via both shared-memory and messages. Synchronisations are realised via message-passing (FIFO queues).

✦ Synchronisation are local (no barriers) and determined by high-level algorithmic patterns. Data races are identified and solved at design time.

✴ Increasing scalability requires to decrease concurrency grain. Programming systems should be designed to support fast data movement and enforce locality.

✦ FastFlow: inter-core communication latency ~7-10 ns on core2 2Ghz. Better than other approaches at fine grain.
ISSUEs for exascale era

✴ How to describe concurrency exploitation at large scale?
  ✦ Parametric patterns. QoS/performance as first-class concept. Couple data with flow-of-control beyond OO (how?)

✴ How we promote scalability “by design” and performance portability?
  ✦ Development tools. Mapping/affinity, should be automatically managed. Graphs very expressive. Graph-to-graph mapping encode semantic-preserving transformation (i.e. optimisation).

✴ Functional-style coding?
  ✦ Empirically the only way I found to write SSE/AVX.